

OS14 Ultra precision controls

OS14-02 Compound fuzzy control- based position tracking accuracy improvement method

Hongfang Chen, Bailing Liu, Ziqi Liang and Zhaoyao Shi
Beijing University of Technology

OS14-04 Effect of Additional Compensator Based on Internal Model Principle in Precision Motion Control

Xuan Gan, Mizuki Takeda and Kaiji Sato
Toyohashi University of Technology

OS14-05 On the Stiff Spring Effect of Linear Ball Guides and its Functions towards Ultra Precise Positioning

Shigeru Futami
THK Co., Ltd.